

# N8262A P-Series Modular Power Meter and Power Sensors



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## Specification Definitions

There are two types of product specifications:

### Warranted specifications

Warranted specifications are specifications which are covered by the product warranty and apply over 0 to 55 °C unless otherwise noted. Warranted specifications include measurement uncertainty calculated with a 95% confidence.

### Characteristic specifications

Characteristic specifications are specifications that are not warranted. They describe product performance that is useful in the application of the product. These characteristic specifications are shown in italics.

Characteristic information is representative of the product. In many cases, it may also be supplemental to a warranted specification.

Characteristic specifications are not verified on all units. There are several types of characteristic specifications. These types can be placed in two groups:

One group of characteristic types describes 'attributes' common to all products of a given model or option. Examples of characteristics that describe 'attributes' are product weight, and 50 ohm input Type-N connector. In these examples' product weight is an 'approximate' value and a 50 ohm input is 'nominal'. These two terms are most widely used when describing a product's 'attributes'.

The second group describes 'statistically' the aggregate performance of the population of products.

These characteristics describe the expected behavior of the population of products. They do not guarantee the performance of any individual product. No measurement uncertainty value is accounted for in the specification. These specifications are referred to as 'typical'.

### Conditions

The power meter and sensor will meet its specifications when:

- Stored for a minimum of two hours at a stable temperature within the operating temperature range, and turned on for at least 30 minutes
- The power meter and sensor are within their recommended calibration period, and
- Used in accordance to the information provided in the N8262A P-Series Modular Power Meter User's Guide

## Using the N8262A P-Series power meter with BenchVue software

The N8262A P-Series power meter is supported by Keysight BenchVue software's BV0007B Power Meter/Sensor Control and Analysis app. Keysight BenchVue software for the PC accelerates testing by providing intuitive, multiple instrument measurement visibility and data capture with no programming necessary. You can derive answers faster than ever by easily viewing, capturing and exporting measurement data and screen shots.

### General features

| Number of channels   | Dual channel   |
|----------------------|--|
| Frequency range      | N1921A P-Series wideband power sensor, 50 MHz to 18 GHz<br>N1922A P-Series wideband power sensor, 50 MHz to 40 GHz   |
| Measurements         | Average, peak and peak-to-average ratio power measurements are provided with free-run or time gated definition. Time parameter measurements of pulse rise time, fall time, pulse width, time to positive occurrence and time to negative occurrence are also provided. |
| Sensor compatibility | P-Series modular power meter is compatible with all Keysight P-Series wideband power sensors, E-Series power sensors (except E9320 range) and 8480 Series power sensors <sup>1</sup> .   |

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1. Information contained in this document refers to operation with P-Series power sensors. For specifications when used with 8480 and E-Series power sensors (except E9320 range), refer to Lit Number 5965-6382E.

# P-Series Modular Power Meter and Sensor

## Key system specifications and characteristics <sup>2</sup>

|                                    |   |
|------------------------------------|---|
| Maximum sampling rate              | 100 Msamples/sec, continuous sampling                                     |
| Video bandwidth                    | ≥ 30 MHz  |
| Single shot bandwidth              | ≥ 30 MHz  |
| Rise time and fall time            | ≤ 13 ns (for frequencies ≥ 500 MHz) <sup>1</sup> , see Figure 1           |
| Minimum pulse width                | 50 ns <sup>2</sup>  |
| Overshoot                          | ≤ 5% <sup>1</sup>   |
| Average power measurement accuracy | N1921A: ≤ ± 0.2 dB or ± 4.5% <sup>3</sup><br>N1922A: ≤ ± 0.3 dB or ± 6.7% |
| Dynamic range                      | -35 to +20 dBm (> 500 MHz)<br>-30 to +20 dBm (50 to 500 MHz)              |
| Maximum capture length             | 1 second  |
| Maximum pulse repetition rate      | 10 MHz (based on 10 samples per period)                                   |

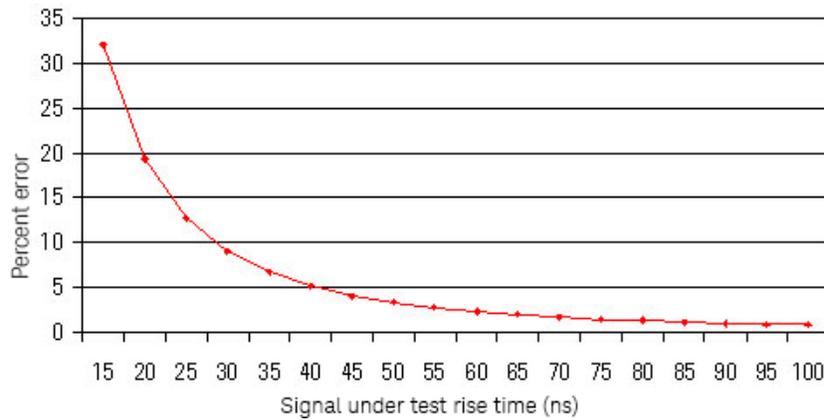


Figure 1. Measured rise time percentage error versus signal under test rise time.

Although the rise time specification is ≤ 13 ns, this does not mean that the P-Series meter and sensor combination can accurately measure a signal with a known rise time of 13 ns. The measured rise time is the root sum of the squares (RSS) of the signal under test rise time and the system rise time (13 ns):

Measured rise time =  $\sqrt{((\text{signal under test rise time})^4 + (\text{system rise time})^4)}$ , and the % error is:

- % Error =  $((\text{measured rise time} - \text{signal under test rise time}) / \text{signal under test rise time}) \times 100$

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1. Specification applies only when the Off video bandwidth is selected.  
 2. The Minimum Pulse Width is the recommended minimum pulse width viewable on the power meter, where power measurements are meaningful and accurate, but not warranted.  
 3. Specification is valid over -15 to +20 dBm, and a frequency range 0.5 to 10 GHz, DUT Max. SWR < 1.27 for the N1921A, and a frequency range 0.5 to 40 GHz, DUT Max. SWR < 1.2 for the N1922A. Averaging set to 32, in Free Run mode.  
 4. See Appendix A on page 9 for measurement uncertainty calculations.

## P-Series Modular Power Meter Specifications

| Meter uncertainty                       |   |
|---|---|
| Instrumentation linearity               | ± 0.8%  |
| Timebase                                |   |
| Timebase range                          | 2 ns to 100 msec/div  |
| Accuracy                                | ± 10 ppm  |
| Jitter                                  | ≤ 1 ns  |
| Trigger                                 |   |
| Internal trigger                        |   |
| • Range                                 | −20 to +20 dBm  |
| • Resolution                            | 0.1 dB  |
| • Level accuracy                        | ± 0.5 dB  |
| • Latency <sup>1</sup>                  | 160 ns ± 10 ns  |
| • Jitter                                | ≤ 5 ns rms  |
| External TTL trigger input              |   |
| High                                    | > 2.4 V   |
| Low                                     | < 0.7 V   |
| Latency <sup>2</sup>                    | 90 ns ± 10 ns   |
| Minimum trigger pulse width             | 15 ns   |
| Minimum trigger repetition period       | 50 ns   |
| Impedance                               | 50 Ω  |
| Jitter                                  | ≤ 5 ns rms  |
| Maximum trigger                         | 15 V emf from 50 Ω dc (current < 100 mA), or                |
| • Voltage input                         | 60 V emf from 50 Ω dc (pulse width < 1 s, current < 100 mA) |
| External TTL trigger output             |   |
| Low to high transition on trigger event |   |
| High                                    | > 2.4 V   |
| Low                                     | < 0.7 V   |
| Latency <sup>3</sup>                    | 30 ns ± 10 ns   |
| Impedance                               | 50 Ω  |
| Jitter                                  | ≤ 5 ns rms  |
| Trigger delay                           |   |
| Delay range                             | ± 1.0 s, maximum  |
| Delay resolution                        | 1% of delay setting, 10 ns maximum                          |
| Trigger hold-off                        |   |
| Range                                   | 1 μs to 400 ms  |
| Resolution                              | 1% of selected value (to minimum of 10 ns)                  |
| Trigger level threshold hysteresis      |   |
| Range                                   | ± 3 dB  |
| Resolution                              | 0.05 dB   |

- 
1. Internal trigger latency is defined as the delay between the applied RF crossing the trigger level and the meter switching into the triggered state.
  2. External trigger latency is defined as the delay between the applied trigger crossing the trigger level and the meter switching into the triggered state.
  3. External trigger output latency is defined as the delay between the meter entering the triggered state and the output signal switching.

## P-Series Wideband Power Sensor Specifications

The P-Series wideband power sensors are designed for use with the P-Series power meters N1911/12A and the P-Series modular power meter N8262A only.

| Sensor model | Frequency range  | Dynamic range                        | Damage level                                | Connector type |
|--------------|------------------|--------------------------------------|---|----------------|
| N1921A       | 50 MHz to 18 GHz | -35 dBm to +20 dBm ( $\geq$ 500 MHz) | +23 dBm (average power)                     | Type N (m)     |
|              |                  | -30 dBm to +20 dBm (50 to 500 MHz)   | +30 dBm (< 1 $\mu$ s duration) (peak power) |                |
| N1922A       | 50 MHz to 40 GHz | -35 dBm to +20 dBm ( $\geq$ 500 MHz) | +23 dBm (average power)                     | 2.4 mm (m)     |
|              |                  | -30 dBm to +20 dBm (50 to 500 MHz)   | +30 dBm (< 1 $\mu$ s duration) (peak power) |                |

## Maximum SWR

| Frequency band   | N1921A/ N1921A | N1922A |
|------------------|----------------|--------|
| 50 MHz to 10 GHz | 1.2            | 1.2    |
| 10 to 18 GHz     | 1.26           | 1.26   |
| 18 to 26.5 GHz   | 1.3            | 1.3    |
| 26.5 to 40 GHz   | 1.5            | 1.5    |

## Sensor Calibration Uncertainty <sup>1</sup>

| Frequency band   | N1921A/ N1921A | N1922A |
|------------------|----------------|--------|
| 50 to 500 MHz    | 4.5%           | 4.3%   |
| 500 MHz to 1 GHz | 4.0%           | 4.2%   |
| 1 to 10 GHz      | 4.0%           | 4.4%   |
| 10 to 18 GHz     | 5.0%           | 4.7%   |
| 18 to 26.5 GHz   |                | 5.9%   |
| 26.5 to 40 GHz   |                | 6.0%   |

| Physical characteristics             |            |                        |
|--------------------------------------|------------|------------------------|
| Dimensions (Length x Width x Height) | N1921A     | 135 mm x 40 mm x 27 mm |
|                                      | N1922A     | 127 mm x 40 mm x 27 mm |
| Weights with cable                   | Option 105 | 0.4 kg                 |
|                                      | Option 106 | 0.6 kg                 |
|                                      | Option 107 | 1.4 kg                 |
| Fixed sensor cable lengths           | Option 105 | 1.5 m (5-feet)         |
|                                      | Option 106 | 3.0 m (10-feet)        |
|                                      | Option 107 | 10 m (31-feet)         |

1. Beyond 70% Humidity, an additional 0.6% should be added to these values.

## Mechanical Characteristic

Mechanical characteristics such as center conductor protrusion and pin depth are not performance specifications. They are, however, important supplemental characteristics related to electrical performance. At no time should the pin depth of the connector be protruding.

## 1 mW Power Reference

Note. The 1 mW power reference is provided for calibration of E-Series (except E9320 range) and 8480 Series power sensors. The P-Series sensors are automatically calibrated and do not need this reference for calibration.

|  |  |
|--|--|
| Power output                           | 1.00 mW (0.0 dBm). Factory set to $\pm 0.4\%$ traceable to the National Physical Laboratory (NPL) UK |
| Accuracy (over 2 years)                | $\pm 1.2\%$ (0 to 55 °C)   |
|  | $\pm 0.4\%$ (25 $\pm$ 10 °C)   |
| Frequency                              | 50 MHz nominal   |
| SWR                                    | 1.08 (0 to 55 °C)  |
|  | 1.05 typical   |
| Connector type                         | Type N (f), 50 $\Omega$  |
| <b>Front panel inputs/outputs</b>      |  |
| Recorder output(s)                     | Analog 0 to 1 volt, 1 k $\Omega$ output impedance. There are two recorder outputs with SMB connector |
| Trigger input                          | Input has TTL compatible logic levels and uses a SMB connector                                       |
| <b>Rear panel inputs/outputs</b>       |  |
| 100BaseT LAN                           | Interface allow communication with an external controller  |
| Ground                                 | Binding post, accepts 4 mm plug or bare-wire connection  |
| Line power                             |  |
| • Input voltage range                  | 100 to 120 V $\pm$ 10%   |
|  | 220 to 240 V $\pm$ 10%   |
| • Input frequency range                | 50 to 60 Hz $\pm$ 10% (all voltages)   |
|  | 400 to 440 Hz (100 to 120 V only)  |
| • Power requirement                    | Not exceeding 75 VA (50 Watts)   |
| <b>Remote programming</b>              |  |
| Interface                              | 10/100BaseT LAN interface  |
| Command language                       | SCPI standard interface commands   |
| <b>Measurement speed</b>               |  |
| Measurement speed via remote interface | $\geq 1500$ readings per second  |
| <b>Regulatory information</b>          |  |
| Electromagnetic compatibility          | Complies with the requirements of the EMC Directive 89/336/EEC                                       |
| Product safety                         | Conforms to the following product specifications:  |
|  | • IEC/EN 61010-1   |
|  | • EN 55011:1991  |
|  | • IEC 61326-1:1997+A1:1998/EN 61326-1:1997+A1:1998   |
|  | • CISPR 11:1990/EN 55011:1991  |
|  | • Canada: CSA C22.2 No. 61010-1:2004   |
| • USA: UL:61010-1:2004                 |  |

| Physical characteristics          |   |
|-----------------------------------|---|
| Dimensions                        | The following dimensions exclude front and rear panel protrusions:<br>44.2 mm H x 212.6 mm W x 420.3 mm D (1.75 in x 8.5 in x 19.63 in) |
| Net weight                        | ≤ 3.5 kg (7.7 lb) approximate   |
| Shipping weight                   | ≤ 7.7 kg (17.0 lb) approximate  |
| Environmental conditions          |   |
| General                           | Complies with the requirements of the EMC Directive 89/336/EEC.   |
| Operating                         |   |
| Temperature                       | 0 to 55 °C  |
| Maximum humidity                  | 95% at 40 °C (non-condensing)   |
| Minimum humidity                  | 15% at 40 °C (non-condensing)   |
| Maximum altitude                  | 3,000 meters (9,840 feet)   |
| Storage                           |   |
| Non-operating storage temperature | -40 to +70 °C   |
| Non-operating maximum humidity    | 90% at 65 °C (non-condensing)   |
| Non-operating maximum altitude    | 15,420 meters (50,000 feet)   |

## System Specifications and Characteristics

The video bandwidth in the power meter can be set to High, Medium, Low or Off. The video bandwidths stated in the table below are not the 3 dB bandwidths, as the video bandwidths are corrected for optimal flatness (except the Off filter). Refer to Figure 2 for information on the flatness response. The Off video bandwidth setting provides the warranted rise time and fall time specification and is the recommended setting for minimizing overshoot on pulse signals.

| Dynamic response - rise time, fall time, and overshoot versus video bandwidth settings |                         |                |              |           |           |
|--|-------------------------|----------------|--------------|-----------|-----------|
| Parameter  | Video bandwidth setting |                |              |           |           |
|  | Low: 5 MHz              | Medium: 15 MHz | High: 30 MHz | Off       |           |
|  |                         |                |              | < 500 MHz | > 500 MHz |
| Rise time/fall time <sup>1</sup>   | < 56 ns                 | < 25 ns        | ≤ 13 ns      | < 36 ns   | ≤ 13 ns   |
| Overshoot <sup>2</sup>   |                         |                |              | < 5 %     | < 5 %     |

For Option 107 (10 m cable), add 5 ns to the rise time and fall time specifications.

1. Specified as 10% to 90% for rise time and 90% to 10% for fall time on a 0 dBm pulse.

2. Specified as the overshoot r For Option 107 (10 m cable), add 5 ns to the rise time and fall time specifications relative to the settled pulse top power.

## Recorder Output and Video Output

The recorder output is used to output the corresponding voltage for the measurement that user sets on the Upper/Lower window of the power meter.

The video output is the direct signal output detected by the sensor diode, with no correction applied. The video output provides a DC voltage proportional to the measured input power through a BNC connector on the rear panel. The DC voltage can be displayed on an oscilloscope for time measurement. This option replaces the recorder output on the rear panel. The video output impedance is 50 ohm.

## Characteristic Peak Flatness

The peak flatness is the flatness of a peak-to-average ratio measurement for various tone-separations for an equal magnitude two-tone RF input. Figure 2 refers to the relative error in peak-to-average ratio measurements as the tone separation is varied. The measurements were performed at -10 dBm with power sensors with 1.5 m cable lengths.

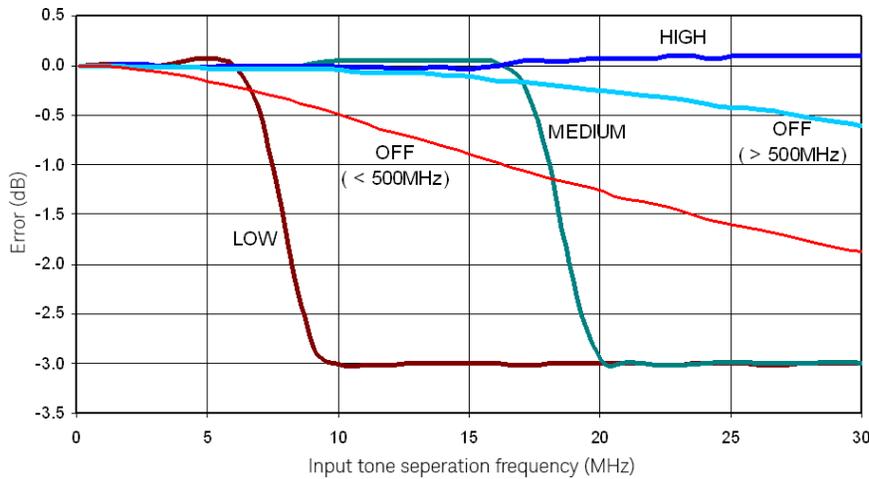


Figure 2. N192XA Error in peak-to-average measurements for a two-tone input (High, Medium, Low or Off filters)

| Noise and drift |                |           |           |                         |                  |   |
|-----------------|----------------|-----------|-----------|-------------------------|------------------|---|
| Sensor model    | Zeroing        | Zero set  |           | Zero drift <sup>1</sup> | Noise per sample | Measurement noise (Free run) <sup>2</sup> |
|                 |                | < 500 MHz | > 500 MHz |                         |                  |   |
| N1921A/N1922A   | No RF on input | ± 200 nW  | ± 200 nW  | 100 nW                  | 2 μW             | 50 nW                                     |
|                 | RF present     | ± 550 nW  | ± 200 nW  |                         |                  |   |

1. Within 1 hour after a zero, at a constant temperature, after 24-hour warm-up of the power meter. This component can be disregarded with Auto-zero mode set to ON.
2. Measured over a one-minute interval, at a constant temperature, two standard deviations, with averaging set to 1.

| Measurement average setting | 1 | 2   | 4   | 8   | 16  | 32  | 64   | 128 | 256 | 512  | 1024 |
|-----------------------------|---|-----|-----|-----|-----|-----|------|-----|-----|------|------|
| Free run noise multiplier   | 1 | 0.9 | 0.8 | 0.7 | 0.6 | 0.5 | 0.45 | 0.4 | 0.3 | 0.25 | 0.2  |

| Video BW setting            |           | Low 5 MHz | Medium 15 MHz | High 30 MHz | Off |
|-----------------------------|-----------|-----------|---------------|-------------|-----|
| Noise per sample multiplier | < 500 MHz | 0.5       | 1             | 2           | 1   |
|                             | ≥ 500 MHz | 0.45      | 0.75          | 1.1         | 1   |

## Effect of video bandwidth setting

The noise per sample is reduced by applying the meter video bandwidth filter setting (High, Medium or Low). If averaging is implemented, this will dominate any effect of changing the video bandwidth.

## Effect of time-gating on measurement noise

The measurement noise on a time-gated measurement will depend on the time gate length. 100 averages are carried out every 1 us of gate length. The Noise-per-Sample contribution in this mode can approximately be reduced by  $\sqrt{(\text{gate length}/10 \text{ ns})}$  to a limit of 50 nW.

## Ordering Information

| Model  | Description                                    |
|--------|--|
| N8262A | P-Series modular power meter (LXI-C compliant) |

## Options

| Sensors           | Description  |
|-------------------|--|
| N192xA-105        | P-Series sensors fixed 1.5 m (5 ft) cable length             |
| N192xA-106        | P-Series sensors fixed 3 m (10 ft) cable length              |
| N192xA-107        | P-Series sensors fixed 10 m (31 ft) cable length             |
| Cables            | Description  |
| N1917A            | P-series meter cable adaptor, 1.5 m (5 ft)                   |
| N1917B            | P-Series meter cable adaptor, 3 m (10 ft)                    |
| N1917C            | P-Series meter cable adaptor, 10 m (31 ft)                   |
| N1917D            | P-Series meter cable adaptor, 1.8 m (6 ft)                   |
| N191xA-200        | 11730x cable adaptor   |
| Other accessories | Description  |
| 34131A            | Transit case for half-rack 2U-high instruments (e.g. 34401A) |
| 34161A            | Accessory pouch  |
| N8262A-908        | Rack mount kit (one instrument)                              |
| N8262A-909        | Rack mount kit (two instruments)                             |
| Software          | Description  |
| BV0007B           | BenchVue Power Meter/Sensor Control and Analysis app license |

| Calibration   | Description  |
|---------------|--|
| N8262A-1A7    | ISO17025 calibration data including Z540 compliance  |
| N8262A-A6J    | ANSI Z540 compliant calibration test data  |
| R-50C-011-3   | Calibration Assurance Plan - Return to Keysight - 3 years  |
| R-50C-011-5   | Calibration Assurance Plan - Return to Keysight - 5 years  |
| R-50C-021-3   | ANSI Z540-1-1994 Calibration up front - 3 years plan   |
| R-50C-021-5   | ANSI Z540-1-1994 Calibration up front - 5 years plan   |
| Documentation | Description  |
| N8262A-0B1    | Hard copy English language User's Guide and Installation Guide                                     |
| N8262A-0BF    | Hard copy English language Programming Guide   |
| N8262A-0BK    | Hard copy English language User's Guide and Programming Guide                                      |
| N8262A-0BW    | Hard copy English language Service and Calibration Guide   |
| N8262A-ABJ    | Hard copy Japanese localization User's Guide   |
| N192xA-0B1    | Hard copy P-Series sensor English language manual  |
| N8262A-CD1    | Documentation Optical Disk (consists of documentation CD-ROM and Keysight Instruments Control DVD) |

## Standard-shipped accessories

- Power cord

# Appendix A

## Uncertainty calculations for a power measurement (settled, average power)

(Specification values from this document are in **bold italic**, values calculated on this page are underlined.)

| Process   |                        |
|---|------------------------|
| 1. Power level .....  | <input type="text"/> W |
| 2. Frequency .....  | <input type="text"/>   |
| 3. Calculate meter uncertainty:<br>Calculate noise contribution   |                        |
| — If in Free Run mode, Noise = <b>Measurement noise x free run multiplier</b>   |                        |
| — If in Trigger mode, Noise = <b>Noise-per-sample x noise per sample multiplier</b>   |                        |
| — Convert noise contribution to a relative term 1 = Noise/Power .....   | <input type="text"/> % |
| — <b>Instrumentation linearity</b> .....  | <input type="text"/> % |
| — <b>Drift</b> .....  | <input type="text"/> % |
| — RSS of above three terms => <u>Meter uncertainty</u> = .....  | <input type="text"/> % |
| 4. <b>Zero uncertainty</b><br>(Mode and frequency dependent) = Zero set/ <u>Power</u> = .....   | <input type="text"/> % |
| 5. Sensor calibration uncertainty<br>(Sensor, frequency, power and temperature dependent) = .....   | <input type="text"/> % |
| 6. <u>System contribution</u> , coverage factor of 2 ≥ sys <sub>rss</sub> = .....   | <input type="text"/> % |
| (RSS three terms from steps 3, 4 and 5)   |                        |
| 7. Standard uncertainty of mismatch .....   | <input type="text"/>   |
| <b>Max SWR</b> (frequency dependent) = .....  | <input type="text"/>   |
| Convert to reflection coefficient,   ρ <sub>Sensor</sub>   = (SWR-1)/(SWR+1) = .....  | <input type="text"/>   |
| Max DUT SWR (frequency dependent) = .....   | <input type="text"/>   |
| Convert to reflection coefficient,   ρ <sub>DUT</sub>   = (SWR-1)/(SWR+1) = .....   | <input type="text"/>   |
| 8. Combined measurement uncertainty @ k = 1   |                        |
| $U_c = \sqrt{\left(\frac{\text{Max}(\rho_{DUT}) \square \text{Max}(\rho_{Sensor})}{\sqrt{2}}\right)^2 + \left(\frac{\text{sys}_{rss}}{2}\right)^2}$ | <input type="text"/>   |
| Expanded uncertainty, k = 2, = UC • 2 = .....   | <input type="text"/>   |

1 The noise to power ratio is capped for powers > 100 μW, in these cases use: Noise/100 μW.

## Worked Example

### Uncertainty calculations for a power measurement (settled, average power)

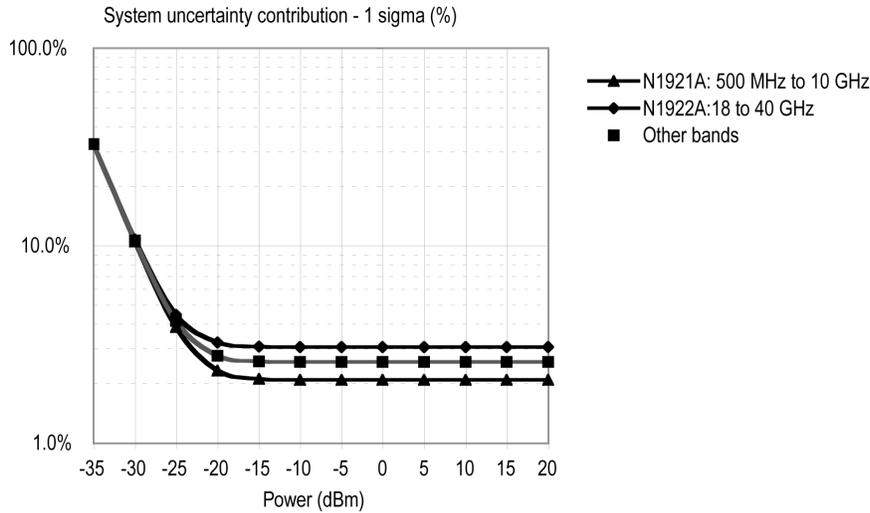
(Specification values from this document are in **bold italic**, values calculated on this page are underlined.)

| Process   |         |
|---|---------|
| 1. Power level .....  | 1mW     |
| 2. Frequency .....  | 1 GHz   |
| 3. Calculate meter uncertainty:<br>Calculate noise contribution   |         |
| — If in Free Run mode, Noise = <b>Measurement noise x free run multiplier</b>   |         |
| — If in Trigger mode, Noise = <b>Noise-per-sample x noise per sample multiplier</b>   |         |
| — Convert noise contribution to a relative term 1 = Noise/Power .....   | 0.03%   |
| — <b>Instrumentation linearity</b> .....  | 0.8%    |
| — <b>Drift</b> .....  | -       |
| — RSS of above three terms => <u>Meter uncertainty</u> = .....  | 0.8%    |
| 4. <b>Zero uncertainty</b><br>(Mode and frequency dependent) = Zero set/Power = .....   | 0.03%   |
| 5. Sensor calibration uncertainty<br>(Sensor, frequency, power and temperature dependent) = .....   | 4.0%    |
| 6. <u>System contribution</u> , coverage factor of 2 ≥ sys <sub>rss</sub> = .....   | 4.08%   |
| (RSS three terms from steps 3, 4 and 5)   |         |
| 7. Standard uncertainty of mismatch<br><b>Max SWR</b> (frequency dependent) = .....   | 1.25    |
| Convert to reflection coefficient,   ρ <sub>Sensor</sub>   = (SWR-1)/(SWR+1) = .....  | 0.111   |
| Max DUT SWR (frequency dependent) = .....   | 1.26    |
| Convert to reflection coefficient,   ρ <sub>DUT</sub>   = (SWR-1)/(SWR+1) = .....   | 2.23    |
| 8. Combined measurement uncertainty @ k = 1   |         |
| $U_c = \sqrt{\left(\frac{\text{Max}(\rho_{DUT}) \square \text{Max}(\rho_{Sensor})}{\sqrt{2}}\right)^2 + \left(\frac{\text{sys}_{rss}}{2}\right)^2}$ ..... | 0.115   |
| Expanded uncertainty, k = 2, = UC • 2 = .....   | ± 4.46% |

1 The noise to power ratio is capped for powers > 100 μW, in these cases use: Noise/100 μW.

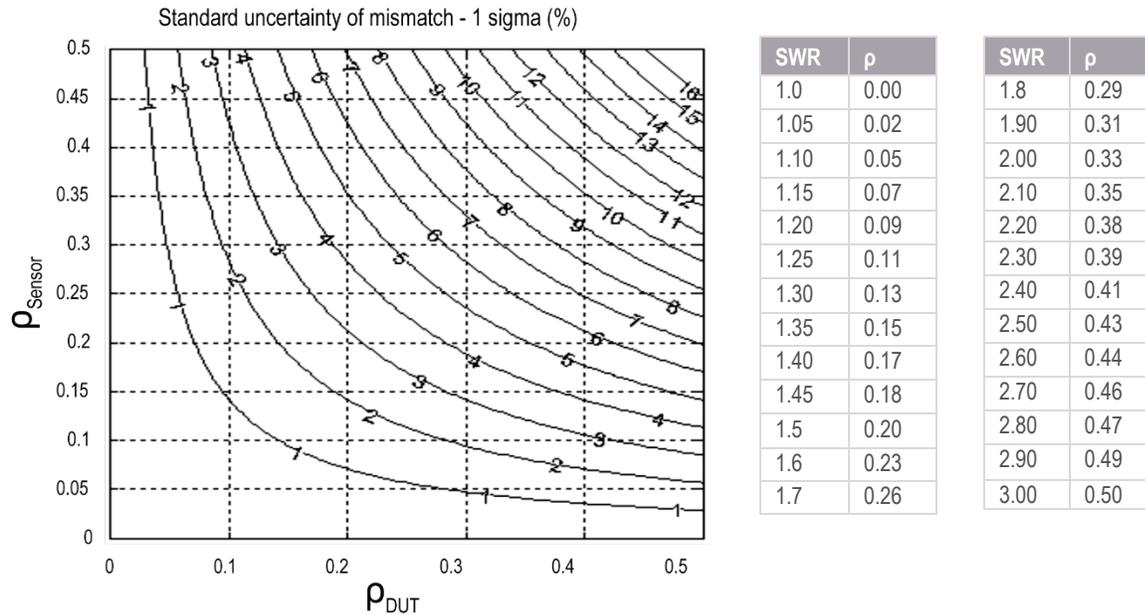
## Graphical Example

### A. System contribution to measurement uncertainty versus power level (equates to step 6 result/2)



Note: This graph is valid for conditions of free-run operation, with a signal within the video bandwidth setting on the system. Humidity < 70%.

### B. Standard uncertainty of mismatch



Note. The above graph shows the standard uncertainty of mismatch =  $\rho_{DUT} \cdot \rho_{Sensor} / \sqrt{2}$ , rather than the mismatch uncertainty limits. This term assumes that both the source and load have uniform magnitude and uniform phase probability distributions.

### C. Combine A and B

$$U_c = \sqrt{(\text{Value from graph A})^2 + (\text{Value from graph B})^2}$$

Expanded uncertainty,  $k = 2$ ,  $= U_c \cdot 2 = \dots\dots\dots$

|   |   |
|---|---|
| ± | % |
|---|---|

### Related Literature List

| Publication title   | Publication number |
|---|--------------------|
| N8262A P-Series Modular Power Meter and Power Sensors - Configuration Guide     | 5989-6608EN        |
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| N8262A P-Series Modular Power Meter - Demo Guide                                | 5989-6636EN        |
| Fundamentals of RF and Microwave Power Measurements (Part 1) - Application Note | 5988-9213EN        |
| Fundamentals of RF and Microwave Power Measurements (Part 2) - Application Note | 5988-9214EN        |
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